

对多元复合函数偏导数求解的研究

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摘要

本文主要讨论多元复合函数的偏导数问题, 主要对中间变量是隐函数的情况进行讨论。文章主线是从隐函数的存在性问题出发, 并结合“链式求导法则、矩阵求多元抽象复合函数二阶偏导数”等技巧和方法, 获得了求解多元复合函数的一、二阶偏导数的理论性定理。

关键词

多元复合函数, 隐函数, 链式法则, 偏导数

Research on Solving Partial Derivatives of Multivariate Compound Functions

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Abstract

In this article, we mainly discuss the partial derivatives of multivariate compound functions, and mainly discuss the case that the intermediate variables are implicit functions. The main line of this article starts from the existence of implicit function, and combines the techniques and methods of “chain derivative rule, using matrix to find the second partial derivative of multiple abstract composite function”. The theoretical theorems for solving the first and second partial derivatives of multivariate compound functions are obtained.

Keywords

Multivariate Compound Functions, Implicit Function, The Chain Rule, Partial Derivatives

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1. 引言

在现已知的多元函数变量代换的方法与应用中，都是仅对复合函数一阶偏导数的代换方法进行了讨论，然而对高阶可微函数的高阶偏导数(如：二阶偏导数)的代换求解公式极少提及。但当我们处理实际问题时，往往会有许多这方面的理论需求，如：多元复合函数的高精度近似计算、多元函数求极值问题等。另外，在对一般复合函数偏导数的计算过程中，常以链式求导法则为主，但在许多具体的问题，例如：函数 $\xi = \xi(z, r)$, $\eta = \eta(z, r)$, $z = (u, v)$, $r = (u, v)$, z, r 为物理域中的变量，而 ξ, η 为计算域中的变量，利用计算域中的结果来讨论自变量变化问题，如果使用链式法则进行计算，求解过程就会极为复杂。故而，为了解决类似的这样一类问题，我们可从隐函数的存在唯一性定理出发，结合[1] [2]中的方法，可得到本文的结果。

2. 预备知识

为后期得到我们的结论，我们先给出如下的隐函数存在唯一性定理和隐函数组定理。

引理 2.1 [3]若函数 $F(x, y)$ 满足下列条件：

- 1) F 在以 $P_0(x_0, y_0)$ 为内点的某一区域 $D \subset R^2$ 上连续；
- 2) $F(x_0, y_0) = 0$ (通常称为初始条件)；
- 3) F 在 D 内存在连续的偏导数 $F_y(x, y)$ ；
- 4) $F_y(x_0, y_0) \neq 0$ 。

则

- i) 存在点 p_0 的某领域 $U(P_0) \subset D$ ，在 $U(P_0)$ 上方程 $F(x, y) = 0$ 唯一地决定了一个定义在某区间 $[x_0 - \alpha, x_0 + \alpha]$ 上的隐函数 $y = f(x)$ ，使得当 $x \in [x_0 - \alpha, x_0 + \alpha]$ 时， $(x, f(x)) \in U(P_0)$ ，且 $F(x, f(x)) = 0$ ， $f(x_0) = y_0$ 。
- ii) $y = f(x)$ 在 $[x_0 - \alpha, x_0 + \alpha]$ 上连续。

引理 2.2 [3]若

- 1) $F(x, y, u, v)$ 与 $G(x, y, u, v)$ 在以点 $P_0(x_0, y_0, u_0, v_0)$ 为内点的区域 $V \subset R^4$ 上连续；
- 2) $F(x_0, y_0, u_0, v_0) = 0$, $G(x_0, y_0, u_0, v_0) = 0$ (初始条件)；
- 3) 在 V 上 F, G 具有一阶连续偏导数；
- 4) $J = \frac{\partial(F, G)}{\partial(u, v)}$ 在点 P_0 不等于 0。

- i) 存在点 P_0 的某一(四维)邻域 $U(P_0) \subset V$ ，在 $U(P_0) \subset V$ 上，方程组 $\begin{cases} F(x, y, u, v) = 0 \\ G(x, y, u, v) = 0 \end{cases}$ ，唯一确定了定义在点 $Q_0(x_0, y_0)$ 的某一(二维空间)邻域 $U(Q_0)$ 上的两个二元隐函数 $u = f(x, y), v = g(x, y)$ ，使得

$u_0 = f(x_0, y_0), v_0 = g(x_0, y_0)$, 且当 $(x, y) \in U(Q_0)$ 时

$$(x, y, f(x, y), g(x, y)) \in U(P_0), \quad F(x, y, f(x, y), g(x, y)) = 0, \quad G(x, y, f(x, y), g(x, y)) = 0;$$

ii) $f(x, y), g(x, y)$ 在 $U(Q_0)$ 上连续;

iii) $f(x, y), g(x, y)$ 在 $U(Q_0)$ 上有一阶连续偏导, 且

$$\frac{\partial u}{\partial x} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(x, v)}, \quad \frac{\partial v}{\partial x} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(u, x)}, \quad \frac{\partial u}{\partial y} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(y, v)}, \quad \frac{\partial v}{\partial y} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(u, y)}$$

为了得到我们的结果, 我们先导出如下定理 2.1:

定理 2.1 设函数 $\xi = \xi(z, r), \eta = \eta(z, r)$ 关于变量 z, r 具有连续的一阶偏导数, 记

$$J = \begin{pmatrix} \frac{\partial \xi}{\partial z} & \frac{\partial \xi}{\partial r} \\ \frac{\partial \eta}{\partial z} & \frac{\partial \eta}{\partial r} \end{pmatrix} \quad (2.1)$$

若 $|J| \neq 0$, 则存在唯一的函数 $z = z(\xi, \eta), r = r(\xi, \eta)$ 满足上述等式并且关于变量 ξ, η 具有连续的一阶偏导数

$$\begin{pmatrix} \frac{\partial z}{\partial \xi} & \frac{\partial z}{\partial \eta} \\ \frac{\partial r}{\partial \xi} & \frac{\partial r}{\partial \eta} \end{pmatrix} = \frac{1}{|J|} \begin{pmatrix} \frac{\partial \eta}{\partial r} & -\frac{\partial \eta}{\partial z} \\ -\frac{\partial \xi}{\partial r} & \frac{\partial \xi}{\partial z} \end{pmatrix} \quad (2.2)$$

其中 $|J|$ 矩阵 J 的行列式。

证明: 假设存在两个不同的坐标系, 中间变量为 (z, r) , 自变量为 (ξ, η) , 两个坐标系存在以下的对应关系:

$$\begin{cases} \xi = \xi(z, r) \\ \eta = \eta(z, r) \end{cases} \quad (2.3)$$

进一步, 令

$$\begin{cases} F(\xi, \eta, \xi(z, r), \eta(z, r)) = \xi - \xi(z, r) = 0 \\ G(\xi, \eta, \xi(z, r), \eta(z, r)) = \eta - \eta(z, r) = 0 \end{cases} \quad (2.4)$$

则由引理 2.2 可知, (2.4) 所对应的 Jacobi 行列式不为 0, 即

$$\frac{\partial(F, G)}{\partial(\xi, \eta)} = \begin{vmatrix} F_\xi & F_\eta \\ G_\xi & G_\eta \end{vmatrix} \neq 0$$

亦即

$$\frac{\partial(F, G)}{\partial(z, r)} = \begin{vmatrix} \frac{\partial F}{\partial z} & \frac{\partial F}{\partial r} \\ \frac{\partial G}{\partial z} & \frac{\partial G}{\partial r} \end{vmatrix} = \begin{vmatrix} -\frac{\partial \xi}{\partial z} & \frac{\partial \xi}{\partial r} \\ -\frac{\partial \eta}{\partial z} & \frac{\partial \eta}{\partial r} \end{vmatrix} \neq 0 \quad (2.5)$$

进而对(2.3)式两边分别关于 ξ, η 求偏导, 则有

$$\frac{\partial \xi}{\partial z} \cdot \frac{\partial z}{\partial \xi} + \frac{\partial \xi}{\partial r} \cdot \frac{\partial r}{\partial \xi} = 1 \quad (2.6)$$

$$\frac{\partial \xi}{\partial z} \cdot \frac{\partial z}{\partial \eta} + \frac{\partial \xi}{\partial r} \cdot \frac{\partial r}{\partial \eta} = 0 \quad (2.7)$$

$$\frac{\partial \eta}{\partial z} \cdot \frac{\partial z}{\partial \xi} + \frac{\partial \eta}{\partial r} \cdot \frac{\partial r}{\partial \xi} = 0 \quad (2.8)$$

$$\frac{\partial \eta}{\partial z} \cdot \frac{\partial z}{\partial \eta} + \frac{\partial \eta}{\partial r} \cdot \frac{\partial r}{\partial \eta} = 1 \quad (2.9)$$

结合(2.6)~(2.9), 易得

$$\begin{pmatrix} \frac{\partial \xi}{\partial z} & \frac{\partial \xi}{\partial r} \\ \frac{\partial \eta}{\partial z} & \frac{\partial \eta}{\partial r} \end{pmatrix} \begin{pmatrix} \frac{\partial z}{\partial \xi} \\ \frac{\partial r}{\partial \xi} \end{pmatrix} = J \begin{pmatrix} \frac{\partial z}{\partial \xi} \\ \frac{\partial r}{\partial \xi} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad (2.10)$$

$$\begin{pmatrix} \frac{\partial \xi}{\partial z} & \frac{\partial \xi}{\partial r} \\ \frac{\partial \eta}{\partial z} & \frac{\partial \eta}{\partial r} \end{pmatrix} \begin{pmatrix} \frac{\partial z}{\partial \eta} \\ \frac{\partial r}{\partial \eta} \end{pmatrix} = J \begin{pmatrix} \frac{\partial z}{\partial \eta} \\ \frac{\partial r}{\partial \eta} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad (2.11)$$

于是有

$$\begin{pmatrix} \frac{\partial z}{\partial \xi} \\ \frac{\partial r}{\partial \xi} \end{pmatrix} = J^{-1} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{|J|} \begin{pmatrix} \frac{\partial \eta}{\partial r} \\ -\frac{\partial \xi}{\partial r} \end{pmatrix} \quad (2.12)$$

$$\begin{pmatrix} \frac{\partial z}{\partial \xi} \\ \frac{\partial r}{\partial \xi} \end{pmatrix} = J^{-1} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{|J|} \begin{pmatrix} -\frac{\partial \eta}{\partial z} \\ \frac{\partial \xi}{\partial z} \end{pmatrix} \quad (2.13)$$

由(2.12)和(2.13)可知(2.2)成立, 证毕。

3. 多元复合函数的一阶、二阶偏导数

遍及本节, 我们有下述假设:

假设 $\omega = f(z, r)$, 且中间变量与自变量之间满足如下关系:

$$\begin{cases} \xi = \xi(z, r) \\ \eta = \eta(z, r) \end{cases}$$

进而对上式两边分别关于 ξ, η 求偏导, 由定理 2.1, 得到:

$$\begin{cases} \frac{\partial z}{\partial \xi} = \frac{1}{|J|} \frac{\partial \eta}{\partial r} \\ \frac{\partial r}{\partial \xi} = -\frac{1}{|J|} \frac{\partial z}{\partial \eta} \\ \frac{\partial \eta}{\partial z} = -\frac{1}{|J|} \frac{\partial r}{\partial \xi} \\ \frac{\partial \eta}{\partial r} = \frac{1}{|J|} \frac{\partial z}{\partial \xi} \end{cases} \quad (3.1)$$

其中

$$J = \begin{pmatrix} \frac{\partial z}{\partial \xi} & \frac{\partial r}{\partial \xi} \\ \frac{\partial z}{\partial \eta} & \frac{\partial r}{\partial \eta} \end{pmatrix}, |J| = \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} - \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \eta} \quad (3.2)$$

接下来，我们首先导出多元复合函数一阶偏导数定理。

定理 3.1 设 $w = f(u, v)$ ，函数 $x = x(u, v), y = y(u, v)$ 关于变量 u, v 具有连续的一阶偏导数，记：

$$J = \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{pmatrix} \quad (3.3)$$

若 $|J| \neq 0$ ，则

$$\begin{pmatrix} \frac{\partial w}{\partial x} \\ \frac{\partial w}{\partial y} \end{pmatrix}^T = \frac{1}{|J|} \begin{pmatrix} \frac{\partial f}{\partial u} & \frac{\partial f}{\partial v} \end{pmatrix} J^{-1} \quad (3.4)$$

证明：依据链式求导法则，有

$$\frac{\partial w}{\partial x} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial x} = \begin{pmatrix} \frac{\partial f}{\partial u} & \frac{\partial f}{\partial v} \end{pmatrix} \begin{pmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial v}{\partial x} \end{pmatrix} \quad (3.5)$$

$$\frac{\partial w}{\partial y} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial y} = \begin{pmatrix} \frac{\partial f}{\partial u} & \frac{\partial f}{\partial v} \end{pmatrix} \begin{pmatrix} \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial y} \end{pmatrix} \quad (3.6)$$

进一步，通过(3.1)式，可以得到

$$\frac{\partial w}{\partial x} = \frac{1}{|J|} \begin{pmatrix} \frac{\partial f}{\partial u} & \frac{\partial f}{\partial v} \end{pmatrix} \begin{pmatrix} \frac{\partial y}{\partial v} \\ -\frac{\partial y}{\partial u} \end{pmatrix} \quad (3.7)$$

$$\frac{\partial w}{\partial y} = \frac{1}{|J|} \begin{pmatrix} \frac{\partial f}{\partial u} & \frac{\partial f}{\partial v} \end{pmatrix} \begin{pmatrix} -\frac{\partial x}{\partial v} \\ \frac{\partial x}{\partial u} \end{pmatrix} \quad (3.8)$$

结合(3.7)~(3.8)，易得(3.4)，证毕。

进一步，我们导出多元复合函数的二阶偏导数定理。

由文献[1]中矩阵求多元抽象复合函数二阶偏导数的方法，可以知道

$$\begin{pmatrix} \frac{\partial^2}{\partial z^2} \end{pmatrix} = \begin{pmatrix} \frac{\partial \xi}{\partial z} & \frac{\partial \eta}{\partial z} \end{pmatrix} \begin{pmatrix} \frac{\partial^2}{\partial \xi^2} & \frac{\partial^2}{\partial \xi \partial \eta} \\ \frac{\partial^2}{\partial \eta \partial \xi} & \frac{\partial^2}{\partial \eta^2} \end{pmatrix} \begin{pmatrix} \frac{\partial \xi}{\partial z} \\ \frac{\partial \eta}{\partial z} \end{pmatrix} + \begin{pmatrix} \frac{\partial}{\partial \xi} & \frac{\partial}{\partial \eta} \end{pmatrix} \begin{pmatrix} \frac{\partial^2 \xi}{\partial z^2} \\ \frac{\partial^2 \eta}{\partial z^2} \end{pmatrix} \quad (3.9)$$

$$\begin{pmatrix} \frac{\partial^2}{\partial \xi^2} \\ \frac{\partial^2}{\partial z \partial \gamma} \end{pmatrix} = \begin{pmatrix} \frac{\partial z}{\partial \xi} & \frac{\partial \gamma}{\partial \xi} \\ \frac{\partial z}{\partial \eta} & \frac{\partial \gamma}{\partial \eta} \end{pmatrix} \begin{pmatrix} \frac{\partial^2}{\partial z^2} & \frac{\partial^2}{\partial z \partial \gamma} \\ \frac{\partial^2}{\partial \eta^2} & \frac{\partial^2}{\partial \eta \partial \gamma} \end{pmatrix} \begin{pmatrix} \frac{\partial z}{\partial \xi} \\ \frac{\partial \gamma}{\partial \xi} \end{pmatrix} + \begin{pmatrix} \frac{\partial}{\partial z} & \frac{\partial}{\partial \gamma} \\ \frac{\partial}{\partial \eta} & \frac{\partial}{\partial \eta} \end{pmatrix} \begin{pmatrix} \frac{\partial^2 z}{\partial \xi^2} \\ \frac{\partial^2 \gamma}{\partial \xi^2} \end{pmatrix} \quad (3.10)$$

进而我们可以得到如下关于多元复合函数求二阶偏导数的定理。

定理 3.2 设 $\omega = f(z, r), \xi = \xi(z, r), \eta = \eta(z, r)$, 且 f, ξ, η 均有连续的二阶偏导数。若记:

$$B = \begin{pmatrix} \left(\frac{\partial r}{\partial \eta} \right)^2 & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & \left(\frac{\partial r}{\partial \xi} \right)^2 \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \xi} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} \\ \left(\frac{\partial z}{\partial \eta} \right)^2 & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & \left(\frac{\partial z}{\partial \xi} \right)^2 \end{pmatrix} \quad (3.11)$$

且满足 $|J| \neq 0$, 则

$$\begin{pmatrix} \frac{\partial^2 \xi}{\partial z^2} \\ \frac{\partial^2 \xi}{\partial z \partial r} \\ \frac{\partial^2 \xi}{\partial r \partial z} \\ \frac{\partial^2 \xi}{\partial r^2} \end{pmatrix} = -\frac{1}{|J|^3} \frac{\partial r}{\partial \eta} B \begin{pmatrix} \frac{\partial^2 z}{\partial \xi^2} \\ \frac{\partial^2 z}{\partial \xi \partial \eta} \\ \frac{\partial^2 z}{\partial \eta \partial \xi} \\ \frac{\partial^2 z}{\partial \eta^2} \end{pmatrix} + \frac{1}{|J|^3} \frac{\partial z}{\partial \eta} B \begin{pmatrix} \frac{\partial^2 r}{\partial \xi^2} \\ \frac{\partial^2 r}{\partial \xi \partial \eta} \\ \frac{\partial^2 r}{\partial \eta \partial \xi} \\ \frac{\partial^2 r}{\partial \eta^2} \end{pmatrix} \quad (3.12)$$

$$\begin{pmatrix} \frac{\partial^2 \eta}{\partial z^2} \\ \frac{\partial^2 \eta}{\partial z \partial r} \\ \frac{\partial^2 \eta}{\partial r \partial z} \\ \frac{\partial^2 \eta}{\partial r^2} \end{pmatrix} = \frac{1}{|J|^3} \frac{\partial r}{\partial \xi} B \begin{pmatrix} \frac{\partial^2 z}{\partial \xi^2} \\ \frac{\partial^2 z}{\partial \xi \partial \eta} \\ \frac{\partial^2 z}{\partial \eta \partial \xi} \\ \frac{\partial^2 z}{\partial \eta^2} \end{pmatrix} - \frac{1}{|J|^3} \frac{\partial z}{\partial \xi} B \begin{pmatrix} \frac{\partial^2 r}{\partial \xi^2} \\ \frac{\partial^2 r}{\partial \xi \partial \eta} \\ \frac{\partial^2 r}{\partial \eta \partial \xi} \\ \frac{\partial^2 r}{\partial \eta^2} \end{pmatrix} \quad (3.13)$$

证明: 对(2.6)和(2.7)两边分别关于 ξ, η 求二阶偏导, 易得

$$\frac{\partial \xi}{\partial z} \cdot \frac{\partial^2 z}{\partial \xi^2} + \frac{\partial z}{\partial \xi} \left[\frac{\partial^2 \xi}{\partial z^2} \cdot \frac{\partial z}{\partial \xi} + \frac{\partial^2 \xi}{\partial z \partial r} \cdot \frac{\partial r}{\partial \xi} \right] + \frac{\partial \xi}{\partial r} \cdot \frac{\partial^2 r}{\partial \xi^2} + \frac{\partial r}{\partial \xi} \left[\frac{\partial^2 \xi}{\partial r \partial z} \cdot \frac{\partial z}{\partial \xi} + \frac{\partial^2 \xi}{\partial r^2} \cdot \frac{\partial r}{\partial \xi} \right] = 0$$

$$\frac{\partial \xi}{\partial z} \cdot \frac{\partial^2 z}{\partial \xi \partial \eta} + \frac{\partial z}{\partial \xi} \left[\frac{\partial^2 \xi}{\partial z^2} \cdot \frac{\partial z}{\partial \eta} + \frac{\partial^2 \xi}{\partial z \partial r} \cdot \frac{\partial r}{\partial \eta} \right] + \frac{\partial \xi}{\partial r} \cdot \frac{\partial^2 r}{\partial \xi \partial \eta} + \frac{\partial r}{\partial \xi} \left[\frac{\partial^2 \xi}{\partial r \partial z} \cdot \frac{\partial z}{\partial \eta} + \frac{\partial^2 \xi}{\partial r^2} \cdot \frac{\partial r}{\partial \eta} \right] = 0$$

$$\frac{\partial \xi}{\partial z} \cdot \frac{\partial^2 z}{\partial \eta \partial \xi} + \frac{\partial z}{\partial \eta} \left[\frac{\partial^2 \xi}{\partial z^2} \cdot \frac{\partial z}{\partial \xi} + \frac{\partial^2 \xi}{\partial z \partial r} \cdot \frac{\partial r}{\partial \xi} \right] + \frac{\partial \xi}{\partial r} \cdot \frac{\partial^2 r}{\partial \xi \partial \eta} + \frac{\partial r}{\partial \eta} \left[\frac{\partial^2 \xi}{\partial r \partial z} \cdot \frac{\partial z}{\partial \xi} + \frac{\partial^2 \xi}{\partial r^2} \cdot \frac{\partial r}{\partial \xi} \right] = 0$$

$$\frac{\partial \xi}{\partial z} \cdot \frac{\partial^2 z}{\partial \eta^2} + \frac{\partial z}{\partial \eta} \left[\frac{\partial^2 \xi}{\partial z^2} \cdot \frac{\partial z}{\partial \eta} + \frac{\partial^2 \xi}{\partial z \partial r} \cdot \frac{\partial r}{\partial \eta} \right] + \frac{\partial \xi}{\partial r} \cdot \frac{\partial^2 r}{\partial \eta^2} + \frac{\partial r}{\partial \eta} \left[\frac{\partial^2 \xi}{\partial r \partial z} \cdot \frac{\partial z}{\partial \eta} + \frac{\partial^2 \xi}{\partial r^2} \cdot \frac{\partial r}{\partial \eta} \right] = 0$$

联立上面 4 个式子, 可得

$$\begin{pmatrix} \left(\frac{\partial z}{\partial \xi} \right)^2 & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \xi} & \left(\frac{\partial r}{\partial \xi} \right)^2 \\ \frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} \\ \frac{\partial z}{\partial \eta} \frac{\partial z}{\partial \xi} & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \xi} & \frac{\partial r}{\partial \eta} \frac{\partial z}{\partial \xi} & \frac{\partial r}{\partial \eta} \frac{\partial r}{\partial \xi} \\ \left(\frac{\partial z}{\partial \eta} \right)^2 & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \eta} \frac{\partial z}{\partial \eta} & \left(\frac{\partial r}{\partial \eta} \right)^2 \end{pmatrix} \begin{pmatrix} \frac{\partial^2 \xi}{\partial z^2} \\ \frac{\partial^2 \xi}{\partial z \partial r} \\ \frac{\partial^2 \xi}{\partial r \partial z} \\ \frac{\partial^2 \xi}{\partial r^2} \end{pmatrix} = - \frac{\partial \xi}{\partial z} \cdot \begin{pmatrix} \frac{\partial^2 z}{\partial \xi^2} \\ \frac{\partial^2 z}{\partial \xi \partial \eta} \\ \frac{\partial^2 z}{\partial \eta \partial \xi} \\ \frac{\partial^2 z}{\partial \eta^2} \end{pmatrix} - \frac{\partial \xi}{\partial r} \cdot \begin{pmatrix} \frac{\partial^2 r}{\partial \xi^2} \\ \frac{\partial^2 r}{\partial \xi \partial \eta} \\ \frac{\partial^2 r}{\partial \eta \partial \xi} \\ \frac{\partial^2 r}{\partial \eta^2} \end{pmatrix} \quad (3.14)$$

记

$$A = \begin{pmatrix} \left(\frac{\partial z}{\partial \xi} \right)^2 & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \xi} & \left(\frac{\partial r}{\partial \xi} \right)^2 \\ \frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} \\ \frac{\partial z}{\partial \eta} \frac{\partial z}{\partial \xi} & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \xi} & \frac{\partial r}{\partial \eta} \frac{\partial z}{\partial \xi} & \frac{\partial r}{\partial \eta} \frac{\partial r}{\partial \xi} \\ \left(\frac{\partial z}{\partial \eta} \right)^2 & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \eta} \frac{\partial z}{\partial \eta} & \left(\frac{\partial r}{\partial \eta} \right)^2 \end{pmatrix} \quad (3.15)$$

为求 A^{-1} , 依据分块矩阵表示方法, A 可写为:

$$\begin{aligned} A &= \begin{pmatrix} \left(\frac{\partial z}{\partial \xi} \right)^2 & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \xi} & \left(\frac{\partial r}{\partial \xi} \right)^2 \\ \frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} \\ \frac{\partial z}{\partial \eta} \frac{\partial z}{\partial \xi} & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \xi} & \frac{\partial r}{\partial \eta} \frac{\partial z}{\partial \xi} & \frac{\partial r}{\partial \eta} \frac{\partial r}{\partial \xi} \\ \left(\frac{\partial z}{\partial \eta} \right)^2 & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \eta} \frac{\partial z}{\partial \eta} & \left(\frac{\partial r}{\partial \eta} \right)^2 \end{pmatrix} \\ &= \begin{pmatrix} \frac{\partial z}{\partial \xi} J & \frac{\partial r}{\partial \xi} J \\ \frac{\partial z}{\partial \eta} J & \frac{\partial r}{\partial \eta} J \end{pmatrix} = \begin{pmatrix} \frac{\partial z}{\partial \xi} E_2 & \frac{\partial r}{\partial \xi} E_2 \\ \frac{\partial z}{\partial \eta} E_2 & \frac{\partial r}{\partial \eta} E_2 \end{pmatrix} \begin{pmatrix} J & 0 \\ 0 & J \end{pmatrix} \end{aligned} \quad (3.16)$$

其中 E_2 是 2×2 阶单位矩阵, J 是(3.3)中所定义的 Jacobi 矩阵。

进一步, 结合(3.1)式, 我们有

$$A^{-1} = \frac{1}{|J|} \begin{pmatrix} J^{-1} & 0 \\ 0 & J^{-1} \end{pmatrix} \begin{pmatrix} \frac{\partial r}{\partial \eta} E_2 & -\frac{\partial r}{\partial \xi} E_2 \\ -\frac{\partial z}{\partial \eta} E_2 & \frac{\partial z}{\partial \xi} E_2 \end{pmatrix}, \quad J^{-1} = \frac{1}{|J|} \begin{pmatrix} \frac{\partial r}{\partial \eta} & -\frac{\partial r}{\partial \xi} \\ -\frac{\partial z}{\partial \eta} & \frac{\partial z}{\partial \xi} \end{pmatrix} \quad (3.17)$$

则可得到

$$A^{-1} = \frac{1}{|J|^2} \begin{pmatrix} \left(\frac{\partial r}{\partial \eta}\right)^2 & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & \left(\frac{\partial r}{\partial \xi}\right)^2 \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \xi} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} \\ \left(\frac{\partial z}{\partial \eta}\right)^2 & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & \left(\frac{\partial z}{\partial \xi}\right)^2 \end{pmatrix} \quad (3.18)$$

结合(3.14), 易得

$$\begin{pmatrix} \frac{\partial^2 \xi}{\partial z^2} \\ \frac{\partial^2 \xi}{\partial z \partial r} \\ \frac{\partial^2 \xi}{\partial r \partial z} \\ \frac{\partial^2 \xi}{\partial r^2} \end{pmatrix} = -\frac{\partial \xi}{\partial z} \cdot A^{-1} \begin{pmatrix} \frac{\partial^2 z}{\partial \xi^2} \\ \frac{\partial^2 z}{\partial \eta \partial \xi} \\ \frac{\partial^2 z}{\partial \eta^2} \end{pmatrix} - \frac{\partial \xi}{\partial r} \cdot A^{-1} \begin{pmatrix} \frac{\partial^2 r}{\partial \xi^2} \\ \frac{\partial^2 r}{\partial \eta \partial \xi} \\ \frac{\partial^2 r}{\partial \eta^2} \end{pmatrix} \quad (3.19)$$

(3.19)左边可化为

$$\begin{aligned}
& \left(\begin{array}{c} \frac{\partial^2 \xi}{\partial z^2} \\ \frac{\partial^2 \xi}{\partial z \partial r} \\ \frac{\partial^2 \xi}{\partial r \partial z} \\ \frac{\partial^2 \xi}{\partial r^2} \end{array} \right) = -\frac{1}{|J|^3} \frac{\partial r}{\partial \eta} \left(\begin{array}{cccc} \left(\frac{\partial r}{\partial \eta} \right)^2 & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & \left(\frac{\partial r}{\partial \xi} \right)^2 \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \xi} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} \\ \left(\frac{\partial z}{\partial \eta} \right)^2 & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & \left(\frac{\partial z}{\partial \xi} \right)^2 \end{array} \right) \left(\begin{array}{c} \frac{\partial^2 z}{\partial \xi^2} \\ \frac{\partial^2 z}{\partial \xi \partial \eta} \\ \frac{\partial^2 z}{\partial \eta \partial \xi} \\ \frac{\partial^2 z}{\partial \eta^2} \end{array} \right) \\
& + \frac{1}{|J|^3} \frac{\partial z}{\partial \eta} \left(\begin{array}{cccc} \left(\frac{\partial r}{\partial \eta} \right)^2 & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & \left(\frac{\partial r}{\partial \xi} \right)^2 \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \xi} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} \\ \left(\frac{\partial z}{\partial \eta} \right)^2 & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & \left(\frac{\partial z}{\partial \xi} \right)^2 \end{array} \right) \left(\begin{array}{c} \frac{\partial^2 r}{\partial \xi^2} \\ \frac{\partial^2 r}{\partial \xi \partial \eta} \\ \frac{\partial^2 r}{\partial \eta \partial \xi} \\ \frac{\partial^2 r}{\partial \eta^2} \end{array} \right)
\end{aligned} \tag{3.20}$$

同理，对(2.8)和(2.9)两边分别关于 ξ, η 求偏导，可得

$$\begin{aligned} \begin{pmatrix} \frac{\partial^2 \eta}{\partial z^2} \\ \frac{\partial^2 \eta}{\partial z \partial r} \\ \frac{\partial^2 \eta}{\partial r \partial z} \\ \frac{\partial^2 \eta}{\partial r^2} \end{pmatrix} &= \frac{1}{|J|^3} \frac{\partial r}{\partial \xi} \begin{pmatrix} \left(\frac{\partial r}{\partial \eta}\right)^2 & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & \left(\frac{\partial r}{\partial \xi}\right)^2 \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \xi} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} \\ \left(\frac{\partial z}{\partial \eta}\right)^2 & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & \left(\frac{\partial z}{\partial \xi}\right)^2 \end{pmatrix} \begin{pmatrix} \frac{\partial^2 z}{\partial \xi^2} \\ \frac{\partial^2 z}{\partial \xi \partial \eta} \\ \frac{\partial^2 z}{\partial \eta \partial \xi} \\ \frac{\partial^2 z}{\partial \eta^2} \end{pmatrix} \\ &\quad - \frac{1}{|J|^3} \frac{\partial z}{\partial \xi} \begin{pmatrix} \left(\frac{\partial r}{\partial \eta}\right)^2 & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial r}{\partial \xi} \frac{\partial r}{\partial \eta} & \left(\frac{\partial r}{\partial \xi}\right)^2 \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & \frac{\partial r}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} \\ -\frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \eta} \frac{\partial r}{\partial \xi} & \frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial r}{\partial \xi} \\ \left(\frac{\partial z}{\partial \eta}\right)^2 & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & -\frac{\partial z}{\partial \xi} \frac{\partial z}{\partial \eta} & \left(\frac{\partial z}{\partial \xi}\right)^2 \end{pmatrix} \begin{pmatrix} \frac{\partial^2 r}{\partial \xi^2} \\ \frac{\partial^2 r}{\partial \xi \partial \eta} \\ \frac{\partial^2 r}{\partial \eta \partial \xi} \\ \frac{\partial^2 r}{\partial \eta^2} \end{pmatrix}. \end{aligned} \tag{3.21}$$

证毕。

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