

TABLE OF CONTENTS 目 录

A Multi-Degree of Freedom Manipulator Based on Active Vision Positioning

(基于主动视觉定位的多自由度机械手臂控制研究)

J. F. CAI, X. Y. MING, J. LI, X. Y. WANG, W. T. TAN, H. Y. YUAN, S. Q. HU.....75

Adaptive Dynamic Programming Based on Hierarchical Learning

(基于分层学习的自适应动态规划)

Q. LIN, M. S. LI.....91

Research on Key Technologies of Humanoid Robot

(仿人机器人关键技术研究)

F. H. WU, L. D. LI, H. WANG, Y. Y. WANG, J. JIANG, S. CHEN.....97

Study on Application of Flexible Dynamic Visualization Technology in Medical Field

(柔性动态可视化技术在医学领域中的应用研究)

Q. HONG, W. Q. ZHANG.....106